## Geometric means of more than two matrices

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SIAM Linear Algebra conference 2009

## A physical problem

Elasticity experiments [Hearmon, 1952; Moakher, 2006]:
Several experimental measures of either the stiffness tensor or its inverse (compliance tensor).

## Problem

How to average them?

Requirement: Averaging inverses (compliance) should yield the same result as averaging the tensors and then inverting

$$
M(A, B, C, \ldots)^{-1}=M\left(A^{-1}, B^{-1}, C^{-1}, \ldots\right)
$$

In the scalar case, this holds true for the geometric mean

## A mathematical problem

At the same time [Ando-Li-Mathias, 2003; Bhatia, 2005; + others]

## Definition

$$
G M\left(a_{1}, a_{2}, \ldots, a_{k}\right)=\sqrt[k]{a_{1} a_{2} \ldots a_{k}} \quad \text { for scalar } a_{i}>0
$$

## Problem

Find a sensible generalization of the geometric mean to SPD matrices

## What do we expect from a geometric mean?

[Ando-Li-Mathias, 2003]: ten properties that a bona-fide geometric mean should have:

- compatibility with scalars: $G M(A, B, C)=(A B C)^{1 / 3}$ for commuting $A, B, C$
- simmetry: $G M(A, B, C)=G M(B, A, C)=\ldots$
- monotonicity: $A<A^{\prime} \Rightarrow G M(A, B, C)<G M\left(A^{\prime}, B, C\right)$
- Congruence invariance: $G M\left(S^{*} A S, S^{*} B S, S^{*} C S\right)=S^{*} G M(A, B, C) S$
- Inversion invariance: $G M\left(A^{-1}, B^{-1}, C^{-1}\right)=G M(A, B, C)^{-1}$
$\ldots+$ others (concavity, continuity... )


## Remark

These do not define GM uniquely!

## Mean of two matrices

There is already a sound definition of the geometric mean of two matrices

## Definition

$$
G M(A, B)=A\left(A^{-1} B\right)^{1 / 2}
$$

(not what you would expect at first!)

Compatibility with scalars + congruence invariance determine it uniquely

## The geometrical meaning of the geometric mean

Natural Riemannian metric on SPD matrices

$$
d s=\left\|A^{-1 / 2} d A A^{-1 / 2}\right\|_{2}
$$

gets more and more "curved" when $A$ approaches singularity

## Example

In dimension 1, logarithmic scale


## The geometrical meaning of the geometric mean

Natural Riemannian metric on SPD matrices

$$
d s=\left\|A^{-1 / 2} d A A^{-1 / 2}\right\|_{2}
$$

Explicit expression for the geodesic joining $A$ and $B$ :

$$
\gamma(t)=A\left(A^{-1} B\right)^{t} \quad t \in[0,1]
$$

Geometric mean $=$ midpoint of the geodesic!

## Generalizing to $k \geq 3$ matrices

## Problem

How do we define the mean of $k \geq 3$ matrices?
The ALM properties do not define it uniquely!
Idea [Ando-Li-Mathias, 2003]: symmetrization procedure

$$
\begin{array}{ll}
A_{1}=G M(B, C) & A_{2}=G M\left(B_{1}, C_{1}\right) \\
B_{1}=G M(C, A) & B_{2}=G M\left(C_{1}, A_{1}\right) \\
C_{1}=G M(A, B) & C_{2}=G M\left(A_{1}, B_{1}\right)
\end{array}
$$

$A_{i}, B_{i}, C_{i}$ converge to the same matrix $G M_{A L M}(A, B, C)$

## ALM construction

$$
\begin{array}{ll}
A_{1}=G M(B, C) & A_{2}=G M\left(B_{1}, C_{1}\right) \\
B_{1}=G M(C, A) & B_{2}=G M\left(C_{1}, A_{1}\right) \\
C_{1}=G M(A, B) & C_{2}=G M\left(A_{1}, B_{1}\right)
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\end{array}
$$



On the plane (Euclidean metric), converges to the centroid of $A B C$.

## ALM mean: properties

- Constructive definition
- Satisfies the ten ALM properties
- May be generalized to $k=4$ or more: $A_{1}=G M(B, C, D, \ldots)$
- Slow to compute: linear convergence, cost grows as $k$ ! (factorial)


## Problem

Is there a faster algorithm to compute it?

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Is there a faster algorithm to compute another mean that satisfies the ten ALM properties?

## Considering the medians

## Theorem

On the Euclidean plane, the three medians of a triangle meet in the centroid at $2 / 3$ of their length.


No iteration needed! Can we do the same for matrices?

## Considering the medians

In the geometry of SPD matrices, the medians don't meet!


## Considering the medians

In the geometry of SPD matrices, the medians don't meet!
$\ldots$... but the points at $2 / 3$ of the corresponding geodesics are very close


## Algorithm

$A_{1}=$ the point at $2 / 3$ of the geodesic joining $A$ and $G M(B, C)$
$B_{1}=$ the point at $2 / 3$ of the geodesic joining $A$ and $G M(C, A)$
$C_{1}=$ the point at $2 / 3$ of the geodesic joining $A$ and $G M(A, B)$
(They are not the same point!)
$A_{2}, B_{2}, C_{2}$ defined in the same way starting from $A_{1} B_{1} C_{1}$, and so on
Theorem
$A_{i}, B_{i}, C_{i}$ converge to the same matrix $G M_{\text {new }}(A, B, C)$

## Properties of the new mean

- Constructive definition
- Generally different from GM $A L M$
- Satisfies the ten ALM properties
- May be generalized to $k \geq 4$ :
$A_{1}=1 / k$ of the geodesic joining $A$ and $G M(B, C, D, \ldots)$
- Convergence order 3: faster than GMALM
- ... though it still grows as $k$ ! (factorial)


## Some numbers

5
1.92542947898189
2.90969918536362
2.35774114351751
2.61639158463414
2.48316587472793
2.54876054375880
2.51571460655576
2.53217471946628
2.52392903948587
2.52804796243998
2.52598752310721
2.52701749813482
2.52650244948321
2.52675995852183
2.52663120018107
2.52669557839604
2.52666338904971
2.52667948366316
2.52667143634151

## 5

2.59890269690271
2.53027293208879
2.53025171828977
2.53025171828977

## Example

$$
A=\left[\begin{array}{ll}
5 & 2 \\
2 & 1
\end{array}\right] \quad B=\left[\begin{array}{ll}
4 & 3 \\
3 & 3
\end{array}\right] \quad C=\left[\begin{array}{ll}
1 & 0 \\
0 & 5
\end{array}\right]
$$

Shown $\left(A_{i}\right)_{11}$ for both iterations

Elasticity measures, data from [Hearmon, '52] (up to $66 \times 6$ matrices): up to $100 \times$ faster

## New directions

Idea: can we obtain new means from the composition of means with less arguments? E.g.

$$
\begin{gathered}
A, B, C, D \mapsto G M(G M(A, B), G M(C, D)) \\
A, B, C \mapsto G M(A, G M(B, C))
\end{gathered}
$$

We need a new framework to deal with non-symmetric mean-like functions.

## Definition

A quasi-mean is a map that is not symmetric in its arguments, but satisfies the other Ando-Li-Mathias properties (with some technical changes).

## Invariance groups

## Definition

$Q$ quasi-mean, $\sigma$ permutation:

$$
(Q \sigma)\left(A_{1}, A_{2}, A_{3}\right):=Q\left(A_{\sigma(1)}, A_{\sigma(2)}, A_{\sigma(3)}\right)
$$

## Definition

Invariance group of a quasi-mean $Q$ :

$$
I(Q):=\{\text { all } \sigma \text { s.t. } Q \sigma(\ldots)=Q(\ldots)\}
$$

$Q$ quasi-mean $+\{I(Q)=$ all permutations $\} \Rightarrow Q$ is a geometric mean (all ALM properties)

## A positive result

This is a geometric mean of four matrices:

$$
\begin{aligned}
& A, B, C, D \mapsto G M( G M(G M(A, B), G M(C, D)), \\
& G M(G M(A, C), G M(B, D)), \\
&G M(G M(A, D), G M(B, C)))
\end{aligned}
$$



A mean of 4 matrices is reduced to one of 3 : computational advantage ( $4 \times$ to $10 \times$ speedup on the elasticity data)

## Negative results

## Strong assumption

The symmetries of a quasi-mean obtained by composition (like $Q(R(\ldots), S(\ldots))$ ) are only those deriving from the symmetries of the underlying quasi-means (like $Q, R, S$ ) that is, no "unexpected properties" appear

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## Theorem

A geometric mean of $k \geq 5$ matrices cannot be built composing (quasi-)means of less matrices

Idea of the proof: the group of permutations of $k \geq 5$ elements is (nearly) a simple group

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Theorem
If a geometric mean of k\geq5 matrices is obtained via composition of
simpler (quasi-)means + a limit process (like GMALM,GM new), then the ingredients must be means of \(k\) - 1 matrices
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We cannot do any better than the current algorithms

Thanks for your attention!

